

Discrete Dynamic Event Trees for Probabilistic Safety Assessment of Nuclear Power Plants

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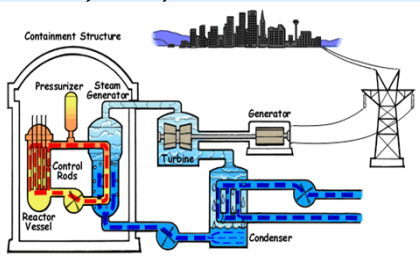
ETH Zürich, May 3rd, 2011

Outline

- Overview of Nuclear Power Plants (NPPs)
- Risk Analysis & Probabilistic Safety Assessment (PSA) Level 1, 2, & 3
 - Fault Tree and Event Tree Approach
 - Use and limitation
- Discrete Dynamic Event Trees (DDETs)
 - Description
 - Applications to PSA
- DDET to support PSA, HRA, & other applications
- Take home messages

NPP overview

NPP (PWR)



Control Room



- Based on concept of **defense-in-depth**
 - multiple, redundant, and independent layers of safety systems
- If **accident**, goal is to lead system in safe conditions
 - automatic systems & control room operators

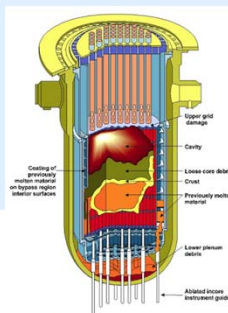
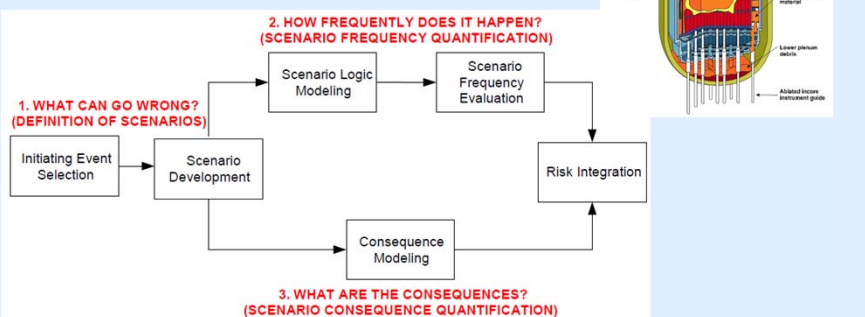
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Risk Analysis

•Risk

- What can go wrong?
- How likely is it?
- What are the consequences?



Probabilistic Risk Assessment Procedures Guide for NASA managers and Practitioners, Office of Safety and Mission Assurance NASA Headquarters Washington, DC 20546

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Probabilistic Safety Assessment

• Approach to risk analysis: Probabilistic Risk/Safety Assessment

- identify the possible accident sequences
- quantify their probabilities and consequences

• PSA is a multilevel analysis technique in respect of the multiple-barrier principle

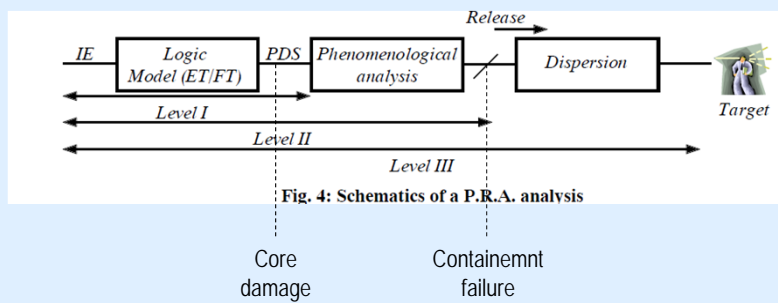
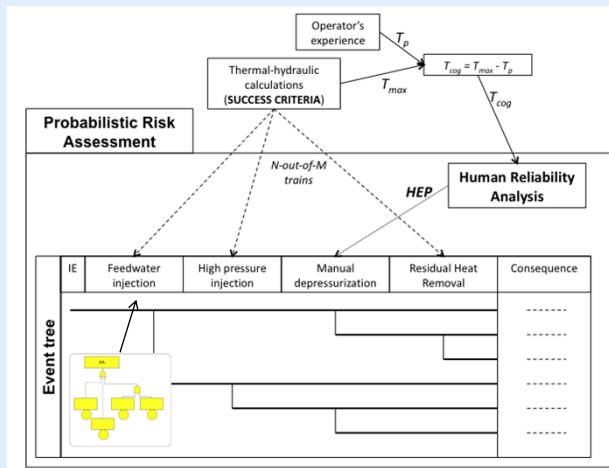


Fig. 4: Schematics of a P.R.A. analysis

Event Trees and Fault Trees

• PSA Level 1 framework



Classical PSA

- Classical PSA is a quasi-static approach
 - Analysis is based on a few thermal-hydraulic calculations
 - Chosen for the most conservative/limiting case by expert
 - Limited evaluation of the effects of the variability of system and operator responses
- In a quasi-static approach is difficult to address:
 - Variability of time & variability of strategies → alternative ways of succeeding
 - Variability of system response
 - Plant effect on crew performance and the vice versa
 - Interactions between them

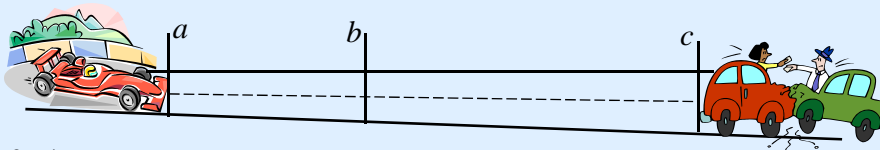


Dynamic approach!

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Example: car accident



• Speed = v

• Classical approach:

- Minimum distance (b) to avoid accident & available time (t_{ab})?
 - Success: at b at v and 100% braking
 - Failure: too late or <100% braking or no action → no action

• Dynamic approach:

- What does the pilot do? What does he see? What is his decision?
- What is the distribution of responses? If response, what braking force is selected?

Model calculates the speed at c → *evaluate the consequences*

Road conditions
Tire conditions
Vehicle type ...

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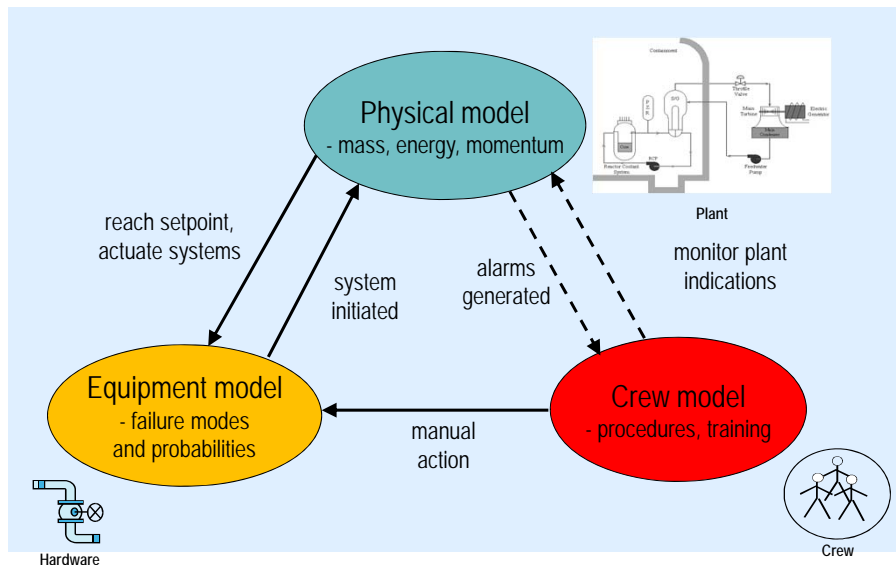
Dynamic Approach

- Attempt to integrate **deterministic** and **stochastic** processes
- Explicitly model the **plant-crew interactions**
- Give **variability** to these interactions
- Model the evolution of the **operator understanding**

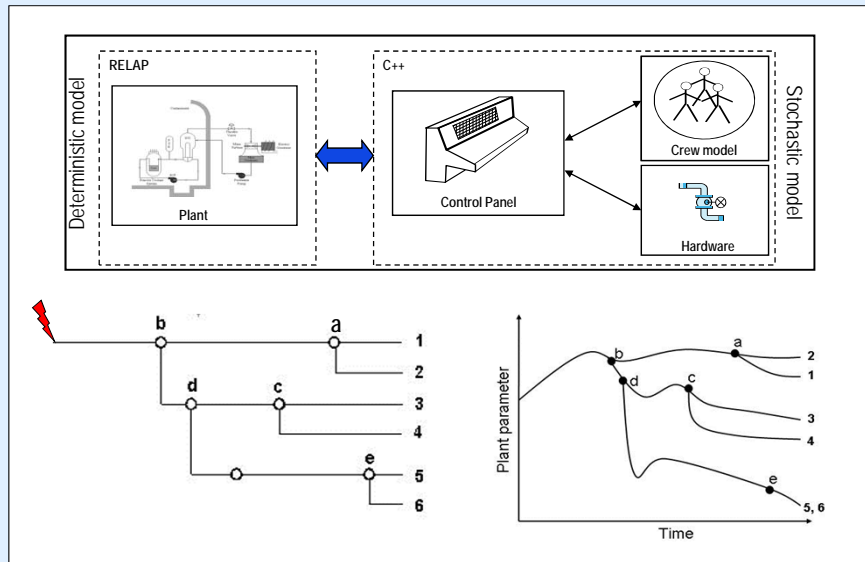


DDET as a mean for dynamic approach!

Dynamic Event Tree – the interacting models



DDET framework

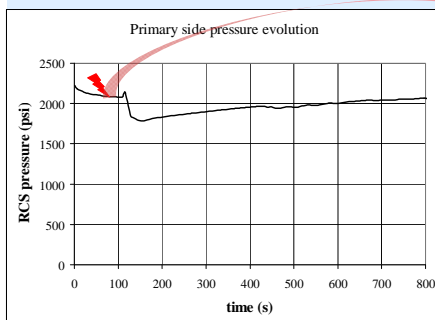


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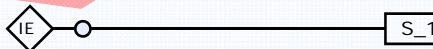
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Dynamic Event Tree evolution

•Parameter evolution



•DET



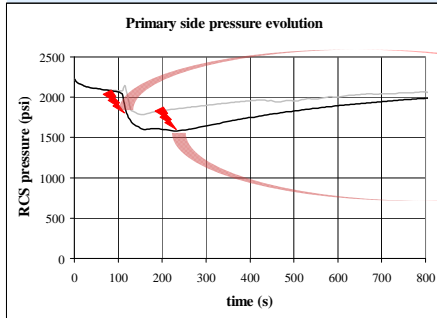
•At each branching point all the parameters are saved in memory

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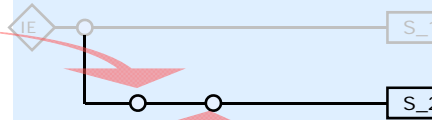
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Dynamic Event Tree evolution

•Parameter evolution



•DET

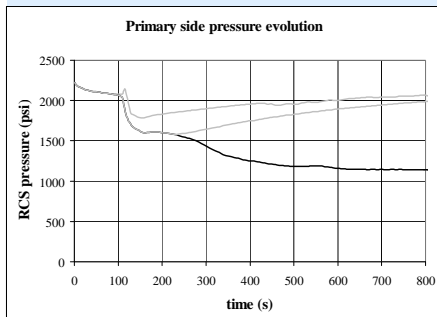


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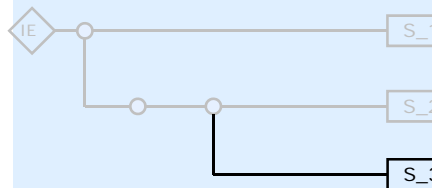
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Dynamic Event Tree evolution

•Parameter evolution



•DET

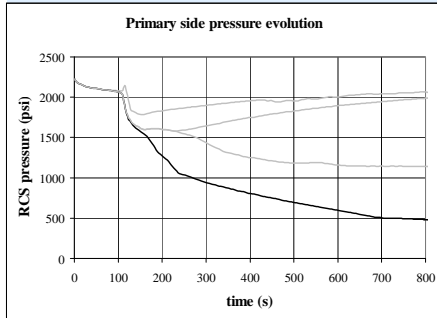


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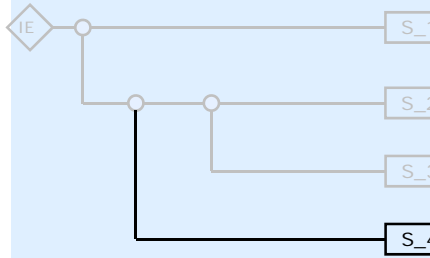
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Dynamic Event Tree evolution

•Parameter evolution



•DET



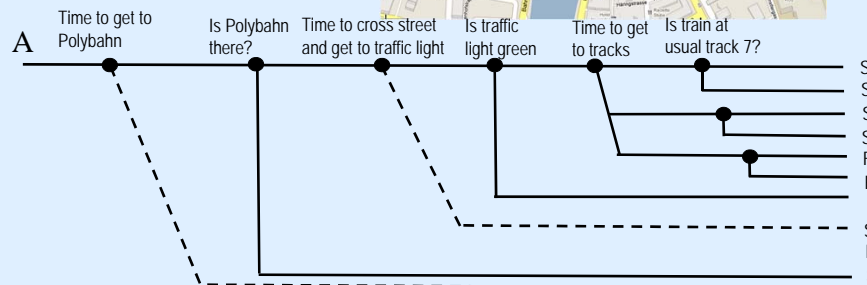
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Example DDET construction

Goal: Go to the train station

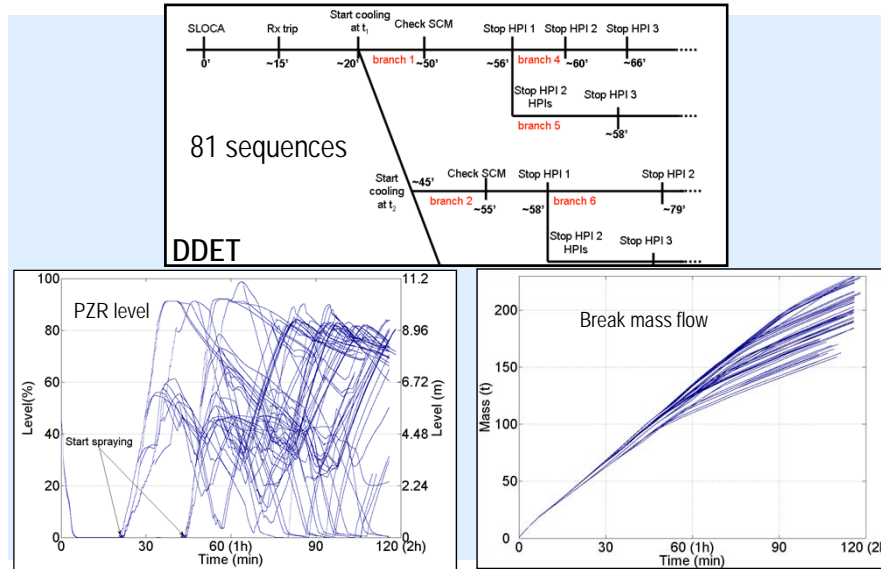
•Many factors will influence the performance:



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Example DDET output



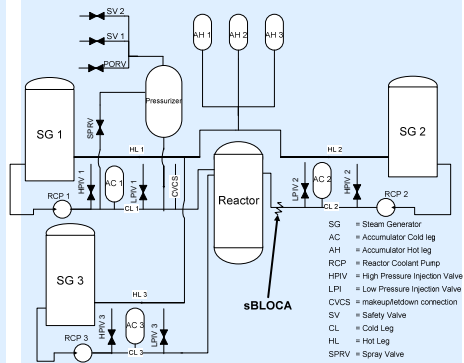
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Example of case study - SLOCA

- Initiating event
 - Leak with diameter of 1 inch in one of the primary side cold legs of a three-loop PWR
 - the break is not sufficient to depressurize and cooldown the primary side
- Main operators' actions after reactor and turbine trips
 - **Cooldown** at 100 K/h through the turbine bypass valves
 - **Depressurize** the system to low pressure conditions
 - **Maintain** the SG levels with the feedwater pumps
 - **Start** the PZR sprays to increase PZR level
 - **Stop** HPI pumps if enough subcooling margin

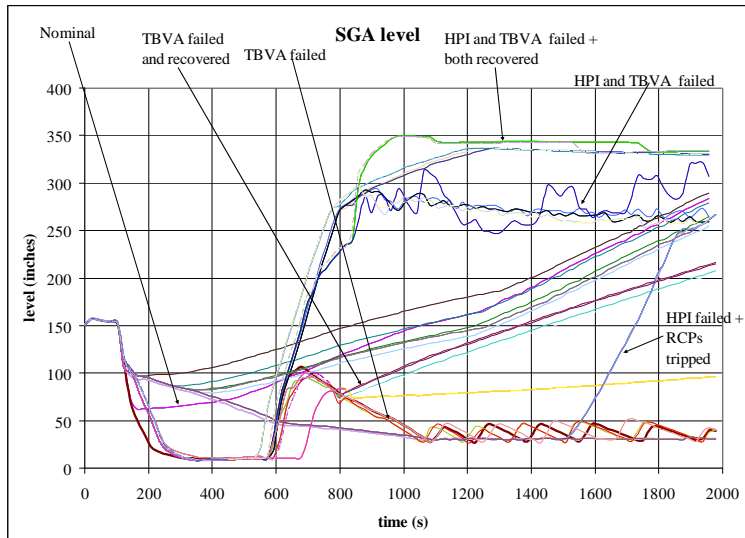
Primary side



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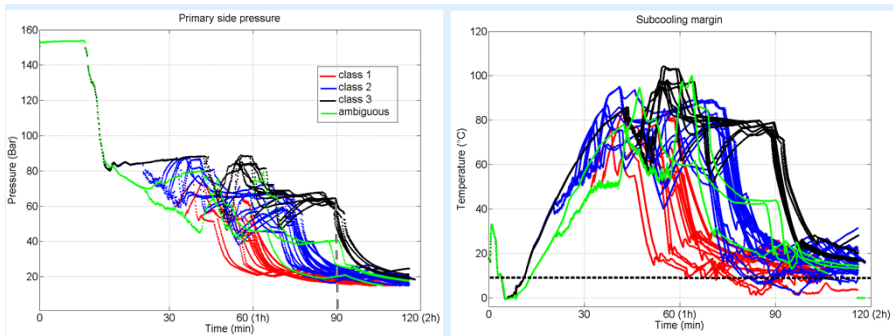
Steam Generator level (all sequences)



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Scenario Analysis



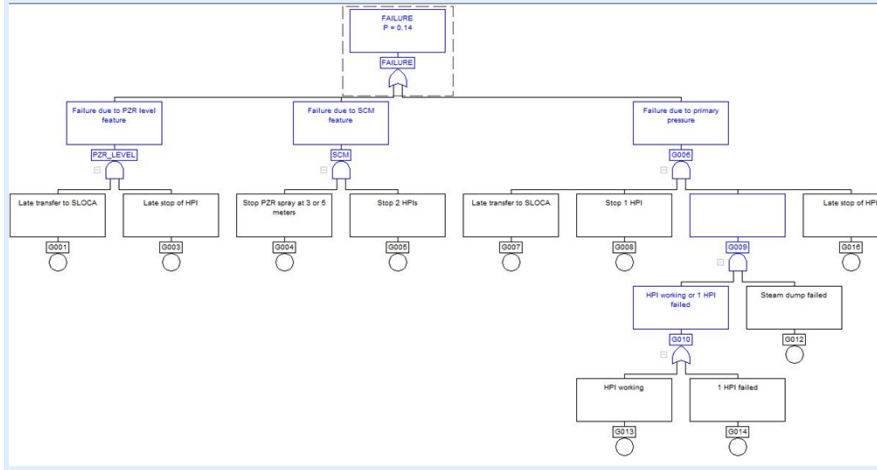
- Post-simulation tools → identification of failure/success scenarios
- Frequency of failure based on frequencies of each sequence

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Failure probability estimation

- Tool extracts information about the contributors to failure



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Human Reliability Analysis

•HRA model

- study the interactions between humans and systems (NPPs)
- attempt to predict the impact of such interactions on the system reliability
- HRA analyst models and quantifies these interactions (HEPs)

•HRA Example: rush to the train station (A to B)



Diagnosis:

Should I stay or should I go?

Executions:

1. Pack your stuff
2. Rush to the Polybahn
3. Cross the street to get to Bahnhofbrücke
4. Cross the street to get to Bahnhof
5. Go to the right track

→ Performance Shaping Factors will influence the response!

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DDET to support HRA (SPAR-H)

Evaluate PSFs for the Diagnosis Portion of the Task, If Any:

PSFs	PSF Levels	Multiplier for Diagnosis	Pie PSF col
Available Time	Inadequate time	P(failure) = 1.0	<input type="checkbox"/>
	Barely adequate time (~2/3 x nominal)	10	<input type="checkbox"/>
	Nominal time	1	<input type="checkbox"/>
	Extra time between 1 and 2 x nominal and > than 30 min)	0.1	<input type="checkbox"/>
	Expansive time (> 2 x nominal and > 30 min)	0.01	<input type="checkbox"/>
Stress/ Stressors	Insufficient information	1	<input type="checkbox"/>
	Extreme	5	<input type="checkbox"/>
	High	2	<input type="checkbox"/>
	Nominal	1	<input type="checkbox"/>
Complexity	Insufficient information	1	<input type="checkbox"/>
	Highly complex	5	<input type="checkbox"/>
	Moderately complex	2	<input type="checkbox"/>
	Nominal	1	<input type="checkbox"/>
Experience/ Training	Obvious diagnosis	0.1	<input type="checkbox"/>
	Insufficient information	1	<input type="checkbox"/>
	Low	10	<input type="checkbox"/>
	High	0.5	<input type="checkbox"/>
Procedures	Insufficient information	1	<input type="checkbox"/>
	Not available	50	<input type="checkbox"/>
	Incomplete	20	<input type="checkbox"/>
	Available, but poor	5	<input type="checkbox"/>
	Nominal	1	<input type="checkbox"/>
Ergonomics/ HMI	Diagnostic/symptom oriented	0.5	<input type="checkbox"/>
	Insufficient information	1	<input type="checkbox"/>
	Missing/Misleading	50	<input type="checkbox"/>
	Poor	10	<input type="checkbox"/>
	Good	0.5	<input type="checkbox"/>
Fitness for Duty	Insufficient information	1	<input type="checkbox"/>
	Unfit	P(failure) = 1.0	<input type="checkbox"/>
	Degraded Fitness	5	<input type="checkbox"/>
	Nominal	1	<input type="checkbox"/>
Work Processes	Insufficient information	1	<input type="checkbox"/>
	Poor	2	<input type="checkbox"/>
	Nominal	1	<input type="checkbox"/>
	Good	0.8	<input type="checkbox"/>
	Insufficient information	1	<input type="checkbox"/>
			<input type="checkbox"/>

• Influence human performance in complex systems → Performance Shaping Factors (PSFs)

• Positive way → low multiplier

• Negative way → high multiplier



$$HEP = f(\text{PSFs})_{\text{Diag}} + f(\text{PSFs})_{\text{Exec}}$$

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Issues from Scenario Analysis

- Not only the variability of time generates different scenarios but also:
 - **Dynamic constraints**
 - Operators cannot shut down 2 pumps because SCM is low → slow crews
 - **Different strategies**
 - Depressurization (fast crews) Vs. maintaining SCM (slow crews)
 - **Competing goals**
 - Quick depressurization vs. high SCM vs. high PZR level
 - Shut 2 HPI pumps → loss of SCM
 - Slowly stop 1 HPI per time → slow depressurization & too high break flow
 - Spray long → loss of SCM

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Support HRA

- SLOCA with HPI systems available
 - PRA → 80' to cooldown & 10' for decision

	SPAR-H	Dynamic
DIAG.	2.5E-2	2.5E-2
EXE.	1.0E-2	5.0E-2
TOT.	3.5E-2	7.5E-2

- Dynamic insights to support PSF evaluation:

- Competing goals
- Dynamic context
- Strategies



PSF complexity increases!!!

- Classical HRA → diagnosis most important
- Dynamic → execution most important!!!

Other applications...

- Success criteria identification
 - A success criterion is a condition that must be verify in order to have the success of the top event in the event tree
 - Based on a few thermal-hydraulic calculations
 - Complete spectrum of potential plant response is not addressed
 - DDETs can support a wide spectrum of plant response due to different system and operator interactions and the edge between success and failure scenarios can be identified
- Uncertainty analysis
 - Probability distributions can be propagated into the DDET to assess the uncertainty boundaries
 - Help Level 2 analysis

Take home messages

- Dynamic approach is a **new research branch** to model and analyze **dynamic interactions** between **plant, automatic systems, and operators**
- **DDET** is a (not “the”) dynamic approach and it is already applied to **accident scenarios analysis** and **support HRA**
- DDET approach could be used in PSA for **success criteria identification** and **uncertainty analysis**